



# Some remarks on a fractional integro-differential inclusion with boundary conditions

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## Abstract

We study the existence of solutions for fractional integrodifferential inclusions of order  $q \in (1, 2]$  with families of mixed, closed, strip and integral boundary conditions. We establish Filippov type existence results in the case of nonconvex set-valued maps.

## 1 Introduction

Differential equations with fractional order have recently proved to be strong tools in the modelling of many physical phenomena. As a consequence there was an intensive development of the theory of differential equations and inclusions of fractional order ([13, 15, 16] etc.). Applied problems require definitions of fractional derivative allowing the utilization of physically interpretable initial conditions. Caputo's fractional derivative, originally introduced in [6] and afterwards adopted in the theory of linear visco elasticity, satisfies this demand. Very recently several qualitative results for fractional integro-differential equations were obtained in [1, 10, 12, 14, 17, 18] etc.

This paper is concerned with the following fractional integro-differential inclusion

$$D_c^q x(t) \in F(t, x(t), V(x)(t)) \quad a.e. ([0, T]), \quad (1)$$

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where  $q \in (1, 2]$ ,  $D_c^q$  is the Caputo fractional derivative,  $F : [0, T] \times \mathbf{R} \times \mathbf{R} \rightarrow \mathcal{P}(\mathbf{R})$  is a set-valued map and  $V : C([0, T], \mathbf{R}) \rightarrow C([0, T], \mathbf{R})$  is a nonlinear Volterra integral operator defined by  $V(x)(t) = \int_0^t k(t, s, x(s))ds$  with  $k(\cdot, \cdot, \cdot) : [0, T] \times \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}$  a given function.

We study (1) subject to four families of boundary conditions:

i) Mixed boundary conditions

$$Tx'(0) = -ax(0) - bx(T), \quad Tx'(T) = bx(0) + dx(T). \quad (2)$$

ii) Closed boundary conditions

$$x(T) = \alpha x(0) + \beta Tx'(0), \quad Tx'(T) = \gamma x(0) + \delta Tx'(0), \quad (3)$$

where  $a, b, d, \alpha, \beta, \gamma, \delta \in \mathbf{R}$  are given constants.

iii) Strip boundary conditions

$$x(0) = \sigma \int_{\alpha}^{\beta} x(s)ds, \quad x(1) = \eta \int_{\gamma}^{\delta} x(s)ds, \quad (4)$$

where  $\sigma, \eta \in \mathbf{R}$  and  $0 < \alpha < \beta < \gamma < \delta < 1$ .

iv) Nonlocal Riemann-Liouville type integral boundary conditions

$$x(0) = aI^{\omega}x(\mu), \quad x(1) = bI^{\nu}x(\theta), \quad (5)$$

where  $a, b \in \mathbf{R}$ ,  $\nu, \omega, \mu, \theta \in (0, 1)$  and  $I^q x(\cdot)$  is the Riemann-Liouville fractional integral of order  $q$ .

The aim of this note is to show that Filippov's ideas ([7]) can be suitably adapted in order to obtain the existence of solutions for problems (1)-(2), (1)-(3), (1)-(4) and (1)-(5). Recall that for a differential inclusion defined by a Lipschitzian set-valued map with nonconvex values, Filippov's theorem ([7]) consists in proving the existence of a solution starting from a given "quasi" solution. Moreover, the result provides an estimate between the "quasi" solution and the solution obtained.

We note that in the case when  $F$  does not depend on the last variable, existence results for problems (1)-(2), (1)-(3), (1)-(4) and (1)-(5) may be found in [7,8,9]. In fact, the results in the present paper extend the main results in [7,8,9] to fractional integrodifferential inclusions.

The paper is organized as follows: in Section 2 we recall some preliminary results that we need in the sequel and in Section 3 we prove our main results.

## 2 Preliminaries

Let  $(X, d)$  be a metric space. Recall that the Pompeiu-Hausdorff distance of the closed subsets  $A, B \subset X$  is defined by

$$d_H(A, B) = \max\{d^*(A, B), d^*(B, A)\}, \quad d^*(A, B) = \sup\{d(a, B); a \in A\},$$

where  $d(x, B) = \inf_{y \in B} d(x, y)$ .

Let  $I = [0, T]$ , we denote by  $C(I, \mathbf{R})$  the Banach space of all continuous functions from  $I$  to  $\mathbf{R}$  with the norm  $\|x(\cdot)\|_C = \sup_{t \in I} |x(t)|$  and  $L^1(I, \mathbf{R})$  is the Banach space of integrable functions  $u(\cdot) : I \rightarrow \mathbf{R}$  endowed with the norm  $\|u(\cdot)\|_1 = \int_0^T |u(t)| dt$ .

**Definition 2.1.** a) The fractional integral of order  $\alpha > 0$  of a Lebesgue integrable function  $f : (0, \infty) \rightarrow \mathbf{R}$  is defined by

$$I^\alpha f(t) = \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} f(s) ds,$$

provided the right-hand side is pointwise defined on  $(0, \infty)$  and  $\Gamma(\cdot)$  is the (Euler's) Gamma function defined by  $\Gamma(\alpha) = \int_0^\infty t^{\alpha-1} e^{-t} dt$ .

b) The Caputo fractional derivative of order  $\alpha > 0$  of a function  $f : [0, \infty) \rightarrow \mathbf{R}$  is defined by

$$D_c^\alpha f(t) = \frac{1}{\Gamma(n-\alpha)} \int_0^t (t-s)^{-\alpha+n-1} f^{(n)}(s) ds,$$

where  $n = [\alpha] + 1$ . It is assumed implicitly that  $f$  is  $n$  times differentiable whose  $n$ -th derivative is absolutely continuous.

We recall (e.g., [13]) that if  $\alpha > 0$  and  $f \in C(I, \mathbf{R})$  or  $f \in L^\infty(I, \mathbf{R})$  then  $(D_c^\alpha I^\alpha f)(t) \equiv f(t)$ .

The next two technical results are proved in [2].

**Lemma 2.2.** The unique solution  $x(\cdot) \in C(I, \mathbf{R})$  of problem

$$D_c^q x(t) = f(t) \quad \text{a.e. } ([0, T]), \tag{6}$$

with boundary conditions (2) is given by  $x(t) = \int_0^T G_1(t, s) f(s) ds$ , where  $G_1(\cdot, \cdot)$  is the Green function defined by

$$G_1(t, s) := \begin{cases} \frac{(t-s)^{q-1}}{\Gamma(q)} - \frac{1}{\Delta_1} \left( \frac{[T(b+d)+(b^2-ad)t](T-s)^{q-1}}{T\Gamma(q)} + \frac{[(a+b)t-(1+b)T](T-s)^{q-2}}{\Gamma(q-1)} \right) & \text{if } 0 \leq s < t \leq T, \\ -\frac{1}{\Delta_1} \left( \frac{[T(b+d)+(b^2-ad)t](T-s)^{q-1}}{T\Gamma(q)} + \frac{[(a+b)t-(1+b)T](T-s)^{q-2}}{\Gamma(q-1)} \right) & \text{if } 0 \leq t < s \leq T, \end{cases}$$

with  $\Delta_1 = (1+b)(b+d) - (a+b)(d-1) \neq 0$ .

Note that

$$|G_1(t, s)| \leq \frac{T^{q-1}}{\Gamma(q)} \cdot \left( 1 + \frac{|b+d+b^2-ad| + (q-1)|a-1|}{|\Delta_1|} \right) =: M_1 \quad \forall t, s \in I.$$

**Lemma 2.3.** *The unique solution  $x(\cdot) \in C(I, \mathbf{R})$  of problem (6)-(3) is given by  $x(t) = \int_0^T G_2(t, s)f(s)ds$ , where the Green function defined by*

$$G_2(t, s) := \begin{cases} \frac{(t-s)^{q-1}}{\Gamma(q)} - \frac{1}{\Delta_2} \left( \frac{[T(1-\delta)+\gamma t](T-s)^{q-1}}{T\Gamma(q)} + \frac{[(1-\alpha)t-(1-\beta)T](T-s)^{q-2}}{\Gamma(q-1)} \right) & \text{if } 0 \leq s < t \leq T, \\ \frac{1}{\Delta_2} \left( \frac{[T(1-\delta)+\gamma t](T-s)^{q-1}}{T\Gamma(q)} + \frac{[(1-\alpha)t-(1-\beta)T](T-s)^{q-2}}{\Gamma(q-1)} \right) & \text{if } 0 \leq t < s \leq T, \end{cases}$$

with  $\Delta_2 = \gamma(1 - \beta) + (1 - \alpha)(1 - \delta) \neq 0$ .

Note that

$$|G_2(t, s)| \leq \frac{T^{q-1}}{\Gamma(q)} \cdot \left( 1 + \frac{|1 - \delta + \gamma| + (q - 1)|\alpha - \beta|}{|\Delta_2|} \right) =: M_2 \quad \forall t, s \in I.$$

For simplicity, in the following results  $T = 1$ .

The next result is proved in [3].

**Lemma 2.4.** *For a given function  $f(\cdot) \in C(I, \mathbf{R})$  the unique solution of problem (6)-(4) is given by*

$$\begin{aligned} x(t) = & \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} f(s) ds + \frac{\sigma}{\Delta} [ -(\frac{\eta}{2}(\delta^2 - \gamma^2) - 1) + \\ & t(\eta(\delta - \gamma) - 1) ] \int_\alpha^\beta \left( \int_0^s \frac{(s-m)^{q-1}}{\Gamma(q)} f(m) dm \right) ds + \frac{1}{\Delta} [ \frac{\sigma}{2}(\beta^2 - \alpha^2) - \\ & (\sigma(\beta - \alpha) - 1)t ] [ \eta \int_\gamma^\delta \left( \int_0^s \frac{(s-m)^{q-1}}{\Gamma(q)} f(m) dm \right) ds - \int_0^1 \frac{(1-s)^{q-1}}{\Gamma(q)} f(s) ds ], \end{aligned}$$

where

$$\Delta = [ \frac{\eta}{2}(\delta^2 - \gamma^2) - 1 ] [ \sigma(\beta - \alpha) - 1 ] - [ \frac{\sigma}{2}(\beta^2 - \alpha^2) ] [ \eta(\delta - \gamma) - 1 ] \neq 0.$$

Denote  $A(t, s) = \frac{(t-s)^{q-1}}{\Gamma(q)} \chi_{[0,t]}(s)$ ,  $B(t, s) = \frac{\sigma}{\Delta\Gamma(q)} [ -(\frac{\eta}{2}(\delta^2 - \gamma^2) - 1) + t(\eta(\delta - \gamma) - 1) ] \frac{1}{q} [ (\beta - s)^q \chi_{[0,\beta]}(s) - (\alpha - s)^q \chi_{[0,\alpha]}(s) ]$ ,  $C(t, s) = \frac{1}{\Delta\Gamma(q)} [ \frac{\sigma}{2}(\beta^2 - \alpha^2) - (\sigma(\beta - \alpha) - 1)t ] \frac{\eta}{q} [ (\delta - s)^q \chi_{[0,\delta]}(s) - (\gamma - s)^q \chi_{[0,\gamma]}(s) ]$ ,  $D(t, s) = -\frac{1}{\Delta\Gamma(q)} [ \frac{\sigma}{2}(\beta^2 - \alpha^2) - (\sigma(\beta - \alpha) - 1)t ] (1-s)^{q-1}$  and  $G_3(t, s) = A(t, s) + B(t, s) + C(t, s) + D(t, s)$ , where  $\chi_S(\cdot)$  is the characteristic function of the set  $S$ . Then the solution  $x(\cdot)$  in Lemma 3 may be written as  $x(t) = \int_0^1 G_3(t, s)f(s)ds$ . Moreover, for any  $t, s \in I$  we have

$$\begin{aligned} |G_3(t, s)| \leq & \frac{1}{\Gamma(q)} + \frac{\sigma}{|\Delta|\Gamma(q)} [ \frac{\eta}{2}(\delta^2 - \gamma^2) - 1 ] + |\eta(\delta - \gamma) - 1| \frac{\beta^q + \alpha^q}{q} + \\ & \frac{1}{|\Delta|\Gamma(q)} [ \frac{\sigma}{2}(\beta^2 - \alpha^2) + |\sigma(\beta - \alpha) - 1| ] [ \frac{\eta}{q}(\delta^q + \gamma^q) + 1 ] =: M_3. \end{aligned}$$

The proof of the following lemma may be found in [4].

**Lemma 2.5.** *For a given  $f(\cdot) \in C(I, \mathbf{R})$  the unique solution of the problem (6)-(5) is given by*

$$x(t) = \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} f(s) ds + (c_1 - tc_4) \int_0^\mu \frac{(\mu-s)^{q+\omega-1}}{\Gamma(q+\omega)} f(s) ds + (c_2 + c_3t) \left[ b \int_0^\theta \frac{(\theta-s)^{q+\nu-1}}{\Gamma(q+\nu)} f(s) ds - \frac{1}{\Gamma(q)} \int_0^1 (1-s)^{q-1} f(s) ds \right],$$

where

$$c_1 = \frac{a}{c} \left( 1 - \frac{b\theta^{\nu+1}}{\Gamma(\nu+2)} \right), \quad c_2 = \frac{a\mu^{\omega+1}}{c\Gamma(\omega+2)}, \quad c_3 = \frac{1}{c} \left( 1 - \frac{a\mu^\omega}{\Gamma(\omega+1)} \right), \quad c_4 = \frac{a}{c} \left( 1 - \frac{b\theta^\nu}{\Gamma(\nu+1)} \right), \\ c = \left( 1 - \frac{a\mu^\omega}{\Gamma(\omega+1)} \right) \left( 1 - \frac{b\theta^{\nu+1}}{\Gamma(\nu+2)} \right) + \frac{a\mu^{\omega+1}}{\Gamma(\omega+2)} \left( 1 - \frac{b\theta^\nu}{\Gamma(\nu+1)} \right).$$

It is implicitly assumed that  $c \neq 0$ .

Denote  $A_1(t, s) = \frac{(t-s)^{q-1}}{\Gamma(q)} \chi_{[0,t]}(s)$ ,  $B_1(t, s) = (c_1 - tc_4) \frac{(\mu-s)^{q+\omega-1}}{\Gamma(q+\omega)} \chi_{[0,\mu]}(s)$ ,  $C_1(t, s) = b(c_2 + c_3t) \frac{(\theta-s)^{q+\nu-1}}{\Gamma(q+\nu)} \chi_{[0,\theta]}(s)$ ,  $D_1(t, s) = -(c_2 + c_3t) \frac{(1-s)^{q-1}}{\Gamma(q)}$  and  $G_4(t, s) = A_1(t, s) + B_1(t, s) + C_1(t, s) + D_1(t, s)$ , then the solution  $x(\cdot)$  in Lemma 4 may be written as  $x(t) = \int_0^1 G_4(t, s) f(s) ds$ . Moreover, for any  $t, s \in I$  we have

$$|G_4(t, s)| \leq \frac{1}{\Gamma(q)} + (|c_1| + |c_4|) \frac{\mu^{q+\omega-1}}{\Gamma(q+\omega)} + |b| (|c_2| + |c_3|) \frac{\theta^{q+\nu-1}}{\Gamma(q+\nu)} + (|c_2| + |c_3|) \frac{1}{\Gamma(q)} =: M_4$$

### 3 The main results

In order to prove our results we need the following hypotheses.

**Hypothesis.** i)  $F(\cdot, \cdot) : I \times \mathbf{R} \times \mathbf{R} \rightarrow \mathcal{P}(\mathbf{R})$  has nonempty closed values and is  $\mathcal{L}(I) \otimes \mathcal{B}(\mathbf{R} \times \mathbf{R})$  measurable.

ii) There exists  $L(\cdot) \in L^1(I, (0, \infty))$  such that, for almost all  $t \in I$ ,  $F(t, \cdot, \cdot)$  is  $L(t)$ -Lipschitz in the sense that

$$d_H(F(t, x_1, y_1), F(t, x_2, y_2)) \leq L(t) (|x_1 - x_2| + |y_1 - y_2|) \quad \forall x_1, x_2, y_1, y_2 \in \mathbf{R}.$$

iii)  $k(\cdot, \cdot, \cdot) : I \times \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}$  is a function such that  $\forall x \in \mathbf{R}$ ,  $(t, s) \rightarrow k(t, s, x)$  is measurable.

iv)  $|k(t, s, x) - k(t, s, y)| \leq L(t) |x - y|$  a.e.  $(t, s) \in I \times I$ ,  $\forall x, y \in \mathbf{R}$ .

We use next the following notations

$$M(t) := L(t) \left( 1 + \int_0^t L(u) du \right), \quad t \in I, \quad M_0 = \int_0^T M(t) dt.$$

**Theorem 3.1.** Assume that Hypothesis is satisfied and  $M_1M_0 < 1$ . Let  $y(\cdot) \in C(I, \mathbf{R})$  be such that  $Ty'(0) = -ay(0) - by(T)$ ,  $Ty'(T) = by(0) + dy(T)$  and there exists  $p(\cdot) \in L^1(I, \mathbf{R}_+)$  with  $d(D_c^q y(t), F(t, y(t), V(y)(t))) \leq p(t)$  a.e. (I).

Then there exists  $x(\cdot) \in C(I, \mathbf{R})$  a solution of problem (1)-(2) satisfying for all  $t \in I$

$$|x(t) - y(t)| \leq \frac{M_1}{1 - M_1M_0} \int_0^T p(t)dt. \quad (7)$$

*Proof.* The set-valued map  $t \rightarrow F(t, y(t), V(y)(t))$  is measurable with closed values and

$$F(t, y(t), V(y)(t)) \cap \{D_c^q y(t) + p(t)[-1, 1]\} \neq \emptyset \quad \text{a.e. (I)}.$$

It follows (e.g., Theorem 1.14.1 in [5]) that there exists a measurable selection  $f_1(t) \in F(t, y(t), V(y)(t))$  a.e. (I) such that

$$|f_1(t) - D_c^q y(t)| \leq p(t) \quad \text{a.e. (I)} \quad (8)$$

Define  $x_1(t) = \int_0^T G_1(t, s)f_1(s)ds$  and one has

$$|x_1(t) - y(t)| \leq M_1 \int_0^T p(t)dt.$$

We claim that it is enough to construct the sequences  $x_n(\cdot) \in C(I, \mathbf{R})$ ,  $f_n(\cdot) \in L^1(I, \mathbf{R})$ ,  $n \geq 1$  with the following properties

$$x_n(t) = \int_0^T G_1(t, s)f_n(s)ds, \quad t \in I, \quad (9)$$

$$f_n(t) \in F(t, x_{n-1}(t), V(x_{n-1})(t)) \quad \text{a.e. (I)}, \quad (10)$$

$$|f_{n+1}(t) - f_n(t)| \leq L(t)(|x_n(t) - x_{n-1}(t)| + \int_0^t L(s)|x_n(s) - x_{n-1}(s)|ds) \quad \text{a.e. (I)} \quad (11)$$

If this construction is realized then from (8)-(11) we have for almost all  $t \in I$

$$|x_{n+1}(t) - x_n(t)| \leq M_1(M_1M_0)^n \int_0^T p(t)dt \quad \forall n \in \mathbf{N}.$$

Indeed, assume that the last inequality is true for  $n - 1$  and we prove it for  $n$ . One has

$$|x_{n+1}(t) - x_n(t)| \leq \int_0^T |G_1(t, t_1)| \cdot |f_{n+1}(t_1) - f_n(t_1)| dt_1 \leq$$

$$M_1 \int_0^T L(t_1) [|x_n(t_1) - x_{n-1}(t_1)| + \int_0^{t_1} L(s) |x_n(s) - x_{n-1}(s)| ds] dt_1 \leq M_1 \int_0^T L(t_1) (1 + \int_0^{t_1} L(s) ds) dt_1 \cdot M_1^n M_0^{n-1} \int_0^T p(t) dt = M_1 (M_1 M_0)^n \int_0^T p(t) dt$$

Therefore  $\{x_n(\cdot)\}$  is a Cauchy sequence in the Banach space  $C(I, \mathbf{R})$ , hence converging uniformly to some  $x(\cdot) \in C(I, \mathbf{R})$ . Therefore, by (11), for almost all  $t \in I$ , the sequence  $\{f_n(t)\}$  is Cauchy in  $\mathbf{R}$ . Let  $f(\cdot)$  be the pointwise limit of  $f_n(\cdot)$ .

Moreover, one has

$$\begin{aligned} |x_n(t) - y(t)| &\leq |x_1(t) - y(t)| + \sum_{i=1}^{n-1} |x_{i+1}(t) - x_i(t)| \leq \\ M_1 \int_0^T p(t) dt + \sum_{i=1}^{n-1} (M_1 \int_0^T p(t) dt) (M_1 M_0)^i &= \frac{M_1 \int_0^T p(t) dt}{1 - M_1 M_0}. \end{aligned} \quad (12)$$

On the other hand, from (8), (11) and (12) we obtain for almost all  $t \in I$

$$\begin{aligned} |f_n(t) - D_c^q y(t)| &\leq \sum_{i=1}^{n-1} |f_{i+1}(t) - f_i(t)| + |f_1(t) - D_c^q y(t)| \leq \\ L(t) \frac{M_1 \int_0^T p(t) dt}{1 - M_1 M_0} + p(t). \end{aligned}$$

Hence the sequence  $f_n(\cdot)$  is integrably bounded and therefore  $f(\cdot) \in L^1(I, \mathbf{R})$ .

Using Lebesgue's dominated convergence theorem and taking the limit in (9), (10) we deduce that  $x(\cdot)$  is a solution of (1)-(2). Finally, passing to the limit in (12) we obtained the desired estimate on  $x(\cdot)$ .

It remains to construct the sequences  $x_n(\cdot), f_n(\cdot)$  with the properties in (9)-(11). The construction will be done by induction.

Since the first step is already realized, assume that for some  $N \geq 1$  we already constructed  $x_n(\cdot) \in C(I, \mathbf{R})$  and  $f_n(\cdot) \in L^1(I, \mathbf{R})$ ,  $n = 1, 2, \dots, N$  satisfying (9), (11) for  $n = 1, 2, \dots, N$  and (10) for  $n = 1, 2, \dots, N - 1$ . The set-valued map  $t \rightarrow F(t, x_N(t), V(x_N)(t))$  is measurable. Moreover, the map  $t \rightarrow L(t) (|x_N(t) - x_{N-1}(t)| + \int_0^t L(s) |x_N(s) - x_{N-1}(s)| ds)$  is measurable. By the lipschitzianity of  $F(t, \cdot)$  we have that for almost all  $t \in I$

$$\begin{aligned} F(t, x_N(t)) \cap \{f_N(t) + L(t) (|x_N(t) - x_{N-1}(t)| + \\ \int_0^t L(s) |x_N(s) - x_{N-1}(s)| ds) [-1, 1]\} \neq \emptyset. \end{aligned}$$

Theorem 1.14.1 in [5] yields that there exist a measurable selection  $f_{N+1}(\cdot)$  of  $F(\cdot, x_N(\cdot), V(x_N)(\cdot))$  such that for almost all  $t \in I$

$$|f_{N+1}(t) - f_N(t)| \leq L(t) (|x_N(t) - x_{N-1}(t)| + \int_0^t L(s) |x_N(s) - x_{N-1}(s)| ds).$$

We define  $x_{N+1}(\cdot)$  as in (9) with  $n = N + 1$ . Thus  $f_{N+1}(\cdot)$  satisfies (10) and (11) and the proof is complete.  $\square$

The proofs of the next three theorems are similar to the proof of Theorem 3.1.

**Theorem 3.2.** Assume that Hypothesis is satisfied and  $M_2M_0 < 1$ . Let  $y(\cdot) \in C(I, \mathbf{R})$  be such that  $y(T) = \alpha y(0) + \beta Ty'(0)$ ,  $Ty'(T) = \gamma y(0) + \delta Ty'(0)$  and there exists  $p(\cdot) \in L^1(I, \mathbf{R})$  with  $d(D_c^q y(t), F(t, y(t), V(y)(t))) \leq p(t)$  a.e. (I).

Then there exists  $x(\cdot) \in C(I, \mathbf{R})$  a solution of problem (1)-(3) satisfying for all  $t \in I$

$$|x(t) - y(t)| \leq \frac{M_2}{1 - M_2M_0} \int_0^T p(t)dt.$$

**Theorem 3.3.** Assume that Hypothesis is satisfied and  $M_3M_0 < 1$ . Let  $y(\cdot) \in C(I, \mathbf{R})$  be such that  $y(0) = \sigma \int_\alpha^\beta y(s)ds$ ,  $y(1) = \eta \int_\gamma^\delta y(s)ds$  and there exists  $p(\cdot) \in L^1(I, \mathbf{R}_+)$  with  $d(D_c^q y(t), F(t, y(t), V(y)(t))) \leq p(t)$  a.e. (I).

Then there exists  $x(\cdot) \in C(I, \mathbf{R})$  a solution of problem (1)-(4) satisfying for all  $t \in I$

$$|x(t) - y(t)| \leq \frac{M_3}{1 - M_3M_0} \int_0^1 p(t)dt.$$

**Theorem 3.4.** Assume that Hypothesis is satisfied and  $M_4M_0 < 1$  Let  $y(\cdot) \in C(I, \mathbf{R})$  be such that  $y(0) = aI^\omega y(\mu)$ ,  $y(1) = bI^\nu y(\theta)$  and there exists  $p(\cdot) \in L^1(I, \mathbf{R}_+)$  with  $d(D_c^q y(t), F(t, y(t), V(y)(t))) \leq p(t)$  a.e. (I).

Then there exists  $x(\cdot) \in C(I, \mathbf{R})$  a solution of problem (1)-(5) satisfying for all  $t \in I$

$$|x(t) - y(t)| \leq \frac{M_4}{1 - M_4M_0} \int_0^1 p(t)dt.$$

**Remark 3.5.** If  $F(\cdot, \cdot, \cdot)$  does not depend on the last variable the fractional integrodifferential inclusion (1) reduces to

$$D_c^q x(t) \in F(t, x(t)) \quad \text{a.e. (I)}$$

and Theorem 3.1 yields Theorem 3.3 in [7], Theorem 3.2 yields Theorem 3.4 in [7], Theorem 3.3 yields Theorem 3.4 in [8] and Theorem 3.4 yields Theorem 3.5 in [9].

## References

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