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APPROXIMATING FIXED POINTS OF NONSELF CONTRACTIVE TYPE MAPPINGS IN BANACH SPACES ENDOWED WITH A GRAPH

Laszlo Balog, Vasile Berinde and Mădălina Păcurar

Dedicated to Professor Ravi P. Agarwal

Abstract

Let K be a non-empty closed subset of a Banach space X endowed with a graph G. We obtain fixed point theorems for nonself G-contractions of Chatterjea type. Our new results complement and extend recent related results [Berinde, V., Păcurar, M., The contraction principle for nonself mappings on Banach spaces endowed with a graph, J. Nonlinear Convex Anal. **16** (2015), no. 9, 1925–1936; Balog, L., Berinde, V., Fixed point theorems for nonself Kannan type contractions in Banach spaces endowed with a graph, Carpathian J. Math. **32** (2016), no. 3 (in press)] and thus provide more general and flexible tools for studying nonlinear functional equations.

1 Introduction

Let X, Y be linear spaces and $F: D \subset X \to Y$ be a nonlinear mapping. One of the most effective ways to solve the equation

$$F(x) = 0, \ x \in D,\tag{1.1}$$

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is to convert it equivalently into a fixed point problem of the form

$$x = T(x), \ x \in K,\tag{1.2}$$

where $T: K \subset X \to X$ is a mapping constructed by a certain scheme.

For example, in the case of the well-known Newton method, considered here for the sake of simplicity in $X = \mathbb{R}$, the iteration function F involved in (1.2) is given by:

$$Tx = x - F(x)/F'(x), x \in K.$$

The equivalent form (1.2) of equation (1.1) is extremely important for at least two major reasons:

- 1. Problem (1.2) can be solved by applying a suitable fixed point theorem, thus obtaining an existence or an existence and uniqueness result for the original problem (1.1);
- 2. The particular form of problem (1.2) now provides a direct way to construct a simple iterative scheme to approximate the solution (s) of (1.1), i.e.,

$$x_{n+1} = Tx_n, \, n \ge 0,$$

with $x_0 \in K$ the starting value.

One of the most important and flexible tools in nonlinear analysis to deal with a problem of the form (1.2) is the well-known Banach contraction principle, stated here in its complete form, see for example [19].

Theorem 1. Let (X, d) be a complete metric space and $T : X \to X$ a strict contraction, i.e., a map satisfying

$$d(Tx, Ty) \le a \, d(x, y) \,, \quad \text{for all } x, y \in X \,, \tag{1.3}$$

where $0 \le a < 1$ is constant. Then:

- (p1) T has a unique fixed point p in X (i.e., Tp = p);
- (p2) The Picard iteration $\{x_n\}_{n=0}^{\infty}$ defined by

$$x_{n+1} = Tx_n, \quad n = 0, 1, 2, \dots$$
 (1.4)

converges to p, for any $x_0 \in X$.

(p3) The following estimate holds

$$d(x_{n+i-1}, p) \le \frac{a^i}{1-a} d(x_n, x_{n-1}), \quad n = 0, 1, 2, \dots; i = 1, 2, \dots$$
(1.5)

As it can be seen from (1.3), Theorem 1 can be applied only to nonlinear equations (1.2) with T a continuous self mapping.

But, most of the concrete problems of the form (1.1) or (1.2) we may encounter in pure and applied mathematics involve generally *discontinuous* and/or *non-self* mappings T. This demand motivated authors to search for more general and more flexible fixed point tools that could be applied to such general nonlinear problems.

Kannan [42] has been the first one to consider in this context discontinuous self mappings T, by considering instead of (1.3) the following alternative and independent contractive condition: there exists a constant $a \in \left[0, \frac{1}{2}\right)$ such

that

 $d(Tx, Ty) \le a \left[d(x, Tx) + d(y, Ty) \right], \quad \text{for all } x, y \in X.$ (1.6)

On the other hand, the study of non-self mappings started with the paper by Caristi [28], in the case of *nonself single-valued* contractions, and with the paper by Assad and Kirk [13], for *non-self multi-valued* contractive mappings $T: K \to \mathcal{P}(X)$, where (X, d) is a convex metric space in the sense of Menger and K is a non-empty closed subset of X.

For some recent and more general results on this topic we refer to [16], [17], [19], [3], [4] and references therein. In a recent paper [20], the second author and M. Păcurar established two fixed point theorems for non self contractions defined on Banach spaces endowed with a graph, while very recently [15], the present authors extended these results to non-self Kannan type contractions $T: X \to X$ on Banach spaces endowed with a graph.

The main aim of the present work is to extend the results in [20] and [15] to the case of mappings satisfying a dual condition of (1.6) which is due to Chatterjea [30] and is independent of both contractive condition (1.3) and (1.6): there exists $a \in (0, \frac{1}{2})$ such that

$$d(Tx,Ty) \le a \left| d(x,Ty) + d(y,Tx) \right|, \quad \text{for all } x, y \in X.$$

$$(1.7)$$

To accomplish this task, we need some basic prerequisites related to fixed point theorems for self and non self contractions in Banach spaces or convex metric spaces endowed with a graph, basically taken from [20] and [15], and which are presented in the next section.

2 Metric spaces endowed with a graph

Let (X, d) be a metric space and let Δ denote the diagonal of the Cartesian product $X \times X$. Consider now a directed simple graph G = (V(G), E(G)) such that the set of its vertices, V(G), coincides with X and E(G), the set of its edges, contains all loops, i.e., $\Delta \subset E(G)$.

By G^{-1} we denote the *converse graph* of G, i.e., the graph obtained by G by reversing its edges, i.e.,

$$E(G^{-1}) = \{(y, x) \in X \times X : (x, y) \in E(G)\}.$$

If x, y are vertices in the graph G, then a *path* from x to y of length N is a sequence $\{x_i\}_{i=1}^N$ of N+1 vertices of G such that

$$x_0 = x, x_N = y$$
 and $(x_{i-1}, x_i) \in E(G), i = 1, 2, \dots, N.$

A graph G is said to be connected if there is at least a path between any two vertices. If G = (V(G), E(G)) is a graph and $H \subset V(G)$, then the graph (H, E(H)) with $E(H) = E(G) \cap (H \times H)$ is called the *subgraph of G determined* by H. Denote it by G_H .

If $\tilde{G} = (X, E(\tilde{G}))$ is the symmetric graph obtained by putting together the vertices of both G and G^{-1} , i.e.,

$$E(\tilde{G}) = E(G) \cup E(G^{-1}),$$

then G is called *weakly connected* if \tilde{G} is connected.

A mapping $T : X \to X$ is said to be (well) defined on a metric space endowed with a graph G if it has the property

$$\forall x, y \in X, (x, y) \in E(G) \text{ implies } (Tx, Ty) \in E(G).$$
(2.1)

According to [41], a mapping $T: X \to X$, which is well defined on a metric space endowed with a graph G, is called a *G*-contraction if there exists a constant $\alpha \in (0, 1)$ such that for all $x, y \in X$ with $(x, y) \in E(G)$ we have

$$d(Tx, Ty) \le \alpha \cdot d(x, y). \tag{2.2}$$

Example 1. If G_0 is the complete graph on X, that is, $E(G_0) = X \times X$, then a G_0 -contraction is a usual contraction in the sense of Banach, i.e., it satisfies condition (1.3), while a G_0 -Kannan contraction is a usual Kannan contraction, i.e., it satisfies condition (1.6).

3 Main results

Let X be a Banach space, K a nonempty closed subset of X and $T: K \to X$ a non-self mapping. If $x \in K$ is such that $Tx \notin K$, then we can always choose an $y \in \partial K$ (the boundary of K) such that $y = (1 - \lambda)x + \lambda T x (0 < \lambda < 1)$, which actually expresses the fact that

$$d(x, Tx) = d(x, y) + d(y, Tx), y \in \partial K,$$
(3.1)

where we denoted d(x, y) = ||x - y||.

In general, the set Y of points y satisfying condition (3.1) above may contain more than one element. We suppose Y is always nonempty.

In this context we shall need the following important concept first introduced and used in [19].

Definition 1. Let X be a Banach space, K a nonempty closed subset of X and $T: K \to X$ a non-self mapping. Let $x \in K$ with $Tx \notin K$ and let $y \in \partial K$ be the corresponding elements given by (3.1). If, for any such elements x, we have

$$d(y, Ty) \le d(x, Tx),\tag{3.2}$$

for all corresponding $y \in Y$, then we say that T has property (M).

Note that the non-self mapping T in the next example has property (M).

Example 2. ([20], Example 4) Let $X = [0,1] \cup \{3\}$ be endowed with the usual norm and let $K = \{0,1,3\}$. Consider the function $T : K \to X$, defined by Tx = 0, for $x \in \{0,1\}$ and T3 = 0.5. As the only value $x \in K$ with $Tx \notin K$ is x = 3 and to it corresponds the set $Y = \{1\}$, and since

$$d(y,Ty) = d(1,T1) = |1 - 0| < |3 - 0.5| = d(3,T3) = d(xTx),$$

property (M) obviously holds.

A condition quite similar to (3.2), called inward condition, has been used by Caristi [28] to obtain a generalization of contraction mapping principle for non self mappings. The inward condition is more general than property (M) since it does not require y in (3.1) to belong to ∂K , see also [37] (this has been communicated to us by Professor Rus [69]).

Note also that, in general, the set Y of points y satisfying condition (3.1) above may contain more than one element.

For a non self mapping $T: K \to X$ we shall say that it is (well) defined on the Banach space X endowed with the graph G if it has this property for the subgraph of G induced by K, that is,

 $(x,y) \in E(G)$ with $Tx, Ty \in K$ implies $(Tx, Ty) \in E(G) \cap (K \times K)$, (3.3)

for all $x, y \in K$.

The next theorem establishes a fixed point theorem for non self Chatterjea contractions defined on a Banach space endowed with a graph.

Theorem 2. Let (X, d, G) be a Banach space endowed with a simple directed and weakly connected graph G such that the property (L) holds, i.e., for any sequence $\{x_n\}_{n=1}^{\infty} \subset X$ with $x_n \to x$ as $n \to \infty$ and $(x_n, x_{n+1}) \in E(G)$ for all $n \in \mathbb{N}$, there exists a subsequence $\{x_{k_n}\}_{n=1}^{\infty}$ satisfying

$$(x_{k_n}, x) \in E(G), \,\forall n \in \mathbb{N}.$$
(3.4)

Let K be a nonempty closed subset of X and let $T : K \to X$ be a Chatterjea contraction, i.e., a mapping for which there exists a constant $a \in [0, 1/2)$ such that

$$d(Tx,Ty) \le a \left[d(x,Ty) + d(y,Tx) \right], \text{ for all } (x,y) \in E(G_K), \tag{3.5}$$

where G_K is the subgraph of G determined by K.

If $K_T := \{x \in \partial K : (x, Tx) \in E(G)\} \neq \emptyset$, T has property (M) satisfies Rothe's boundary condition

$$\Gamma(\partial K) \subset K,\tag{3.6}$$

then

(i) $Fix(T) = \{x^*\};$

(ii) Picard iteration $\{x_n = T^n x_0\}_{n=1}^{\infty}$ converges to x^* , for all $x_0 \in K_T$, and the following estimate holds

$$d(x_n, x^*) \le \frac{\delta^{[n/2]}}{1-\delta} \max\{d(x_0, x_1), d(x_1, x_2)\}, \quad n = 0, 1, 2, \dots$$
(3.7)

where $\delta = \frac{a}{1-a}$.

Proof. If $T(K) \subset K$, then T is actually a self mapping of the closed set K and the conclusion follows by Chatterjea fixed point theorem [30] with X = K. Therefore, in the following we consider only the case $T(K) \not\subset K$. Let $x_0 \in K_T$. This means that $(x_0, Tx_0) \in E(G)$ and in view of (2.1), we have

$$(T^n x_0, T^{n+1} x_0) \in E(G), \,\forall n \in \mathbb{N}.$$
(3.8)

Denote $y_n := T^n x_0$, for all $n \in \mathbb{N}$.

By (3.6) it also follows that $Tx_0 \in K$.

Denote $x_1 := y_1 = Tx_0$. Now, if $Tx_1 \in K$, set $x_2 := y_2 = Tx_1$. If $Tx_1 \notin K$, we can choose an element x_2 on the segment $[x_1, Tx_1]$ which also belong to ∂K , that is,

$$x_{2} = (1 - \lambda)x_{1} + \lambda T x_{1} (0 < \lambda < 1).$$

Continuing in this way we obtain two sequences $\{x_n\}$ and $\{y_n\}$ whose terms satisfy one of the following properties:

i) $x_n := y_n = Tx_{n-1}$, if $Tx_{n-1} \in K$;

ii) $x_n = (1 - \lambda)x_{n-1} + \lambda T x_{n-1} \in \partial K \ (0 < \lambda < 1)$, if $T x_{n-1} \notin K$. To simplify the argumentation in the proof, let us denote

$$P = \{x_k \in \{x_n\} : x_k = y_k = Tx_{k-1}\}$$

and

$$Q = \{x_k \in \{x_n\} : x_k \neq Tx_{k-1}\}.$$

Note that $\{x_n\} \subset K$ for all $n \in \mathbb{N}$ and that, if $x_k \in Q$, then both x_{k-1} and x_{k+1} belong to the set P.

Moreover, by virtue of (3.6), we cannot have two consecutive terms of $\{x_n\}$ in the set Q (but we can have two consecutive terms of $\{x_n\}$ in the set P).

We claim that $\{x_n\}$ is a Cauchy sequence.

To prove this, we must discuss three different cases: Case I. $x_n, x_{n+1} \in P$; Case II. $x_n \in P, x_{n+1} \in Q$; Case III. $x_n \in Q, x_{n+1} \in P$;

Case I. $x_n, x_{n+1} \in P$.

In this case we have $x_n = y_n = Tx_{n-1}$, $x_{n+1} = y_{n+1} = Tx_n$, and hence

$$d(x_{n+1}, x_n) = d(y_{n+1}, y_n) = d(Tx_n, Tx_{n-1}).$$

Since $\{x_n\} \subset K$ for all $n \in \mathbb{N}$, by (3.8) $(x_n, x_{n-1}) \in E(G_K)$, and so by the contraction condition (3.5), we get

$$d(x_{n+1}, x_n) = d(Tx_n, Tx_{n-1}) \le a[d(x_n, Tx_{n-1}) + d(x_{n-1}, Tx_n)]$$
$$= ad(x_{n-1}, x_{n+1}) \le a[d(x_{n-1}, x_n) + d(x_n, x_{n+1})],$$

by triangle inequality, and this leads to

$$d(x_{n+1}, x_n) \le \delta d(x_n, x_{n-1}), \tag{3.9}$$

where $\delta = \frac{a}{1-a}$.

Case II. $x_n \in P$, $x_{n+1} \in Q$. In this case we have $x_n = y_n = Tx_{n-1}$, but $x_{n+1} \neq y_{n+1} = Tx_n$ and

$$d(x_n, x_{n+1}) + d(x_{n+1}, Tx_n) = d(x_n, Tx_n).$$

Thus $d(x_{n+1}, Tx_n) \neq 0$ and hence

$$d(x_n, x_{n+1}) = d(x_n, Tx_n) - d(x_{n+1}, Tx_n) < d(x_n, Tx_n).$$
(3.10)

Now, by a similar argument to that in Case I, $(x_n, x_{n-1}) \in E(G_K)$ and hence by the contraction condition (3.5) we get

$$d(x_n, Tx_n) = d(Tx_{n-1}, Tx_n) \le a[d(x_{n-1}, Tx_n) + d(x_n, Tx_{n-1})]$$
$$= ad(x_{n-1}, Tx_n) \le a[d(x_{n-1}, x_n) + d(x_n, Tx_n)].$$

Thus

$$d(x_n, Tx_n) \le \delta d(x_n, x_{n-1}).$$

and therefore, by means of 3.10,

$$d(x_n, x_{n+1}) < d(x_n, Tx_n) \le \delta d(x_n, x_{n-1}).$$

which is exactly inequality (3.9) obtained in Case I.

Case III. $x_n \in Q, x_{n+1} \in P$. In this case we have $x_{n+1} = Tx_n, x_n \neq y_n = Tx_{n-1}$ and

$$d(x_{n-1}, x_n) + d(x_n, Tx_{n-1}) = d(x_{n-1}, Tx_{n-1}).$$
(3.11)

Hence, by property (M) we get

$$d(x_n, x_{n+1}) = d(x_n, Tx_n) \le d(x_{n-1}, Tx_{n-1}) = d(Tx_{n-2}, Tx_{n-1}).$$

(since $x_n \in Q \Longrightarrow x_{n-1} \in P$). Thus,

$$d(x_n, x_{n+1}) \le d(Tx_{n-2}, Tx_{n-1}).$$

Since, by (3.8), $(y_{n-1}, y_n) \in E(G)$, by the contraction condition (3.5) with $x := x_{n-2}$ and $y := x_{n-1}$ we obtain

$$d(Tx_{n-2}, Tx_{n-1}) \le a[d(x_{n-2}, Tx_{n-1}) + d(x_{n-1}, Tx_{n-2})]$$
$$= ad(x_{n-2}, x_n),$$

since $x_{n-1} = Tx_{n-2}$. Therefore, by triangle inequality,

$$d(x_n, x_{n+1}) \le ad(x_{n-2}, x_n) \le a[d(x_{n-2}, x_{n-1}) + d(x_{n-1}, x_n)]$$

$$= 2a \cdot \frac{d(x_{n-2}, x_{n-1}) + d(x_{n-1}, x_n)}{2} \le 2a \max\{d(x_{n-2}, x_{n-1}), d(x_{n-1}, x_n)\}.$$

Since $\max\{2a, \frac{a}{1-a}\} = \frac{a}{1-a} := \delta$, we finally obtain

$$d(x_n, x_{n+1}) \le \delta d(x_{n-2}, x_{n-1}).$$
(3.12)

Now, by summaryzing all three cases and using (3.9) and (3.12), it follows that the sequence $\{d(x_n, x_{n-1})\}$ satisfies the inequality

$$d(x_n, x_{n+1}) \le \delta \max\{d(x_{n-2}, x_{n-1}), d(x_{n-1}, x_n)\},$$
(3.13)

for all $n \ge 2$. Now, by induction for $n \ge 2$, from (3.13) one obtains

$$d(x_n, x_{n+1}) \le \delta^{\lfloor n/2 \rfloor} \max\{d(x_0, x_1), d(x_1, x_2)\},$$
(3.14)

where [n/2] denotes the greatest integer not exceeding n/2.

Further, for m > n > N,

$$d(x_n, x_m) \le \sum_{i=N}^{\infty} d(x_i, x_{i-1}) \le 2 \frac{\delta^{[N/2]}}{1-\delta} \max\{d(x_0, x_1), d(x_1, x_2)\}, \quad (3.15)$$

which shows that $\{x_n\}$ is a Cauchy sequence.

Since $\{x_n\} \subset K$ and K is closed, $\{x_n\}$ converges to some point x^* in K, i.e.,

$$x^* = \lim_{n \to \infty} x_n. \tag{3.16}$$

By property (L), there exists a subsequence $\{x_{k_n}\}_{n=1}^{\infty}$ of $\{x_n\}_{n=1}^{\infty}$ satisfying

$$(x_{k_n}, x^*) \in E(G), \forall n \in \mathbb{N}.$$

and hence, by the contraction condition (3.5),

$$d(x_{k_n+1}, Tx^*) = d(Tx_{k_n}, Tx^*) \le a[d(x_{k_n}, Tx^*) + d(x^*, Tx_{k_n}]$$
$$\le a[d(x_{k_n}, Tx_{k_n}) + d(Tx_{k_n}, Tx^*) + d(x^*, x_{k_n+1}].$$
$$= a[d(x_{k_n}, Tx_{k_n}) + d(x_{k_n+1}, Tx^*) + d(x^*, x_{k_n+1}].$$

This yields,

$$d(x_{k_n+1}, Tx^*) \le \delta d(x_{k_n}, Tx_{k_n}) + ad(x^*, x_{k_n+1}],$$

which, by means of (3.15) and by letting $n \to \infty$ shows that the sequence $\{x_{k_n}\}_{n=1}^{\infty}$ converges to Tx^* as $n \to \infty$. By (3.16) and the uniqueness of the limit in a metric space, we infer that $x^* = Tx^*$, i.e., x^* is a fixed point of T.

The uniqueness of x^* immediately follows by the contraction condition (3.5), which implies the uniqueness condition

$$d(Tx, Ty) \leq \delta d(x, y) + 2\delta d(x, Tx)$$
, for all $(x, y) \in E(G_K)$.

In the end, by using the estimate (3.14) and triangle inequality we obtain for any $n, p \in \mathbb{N}^*$

$$d(x_n, x_{n+p}) \le \delta^{[n/2]} \frac{1 - \delta^{[(p+1)/2]}}{1 - \delta} \max\{d(x_0, x_1), d(x_1, x_2)\},\$$

from which, by letting $p \to \infty$, we get exactly the error estimate (3.7).

A weaker form of Theorem 2 can be stated as follows.

Theorem 3. Let (X, d, G) be a Banach space endowed with a simple directed and weakly connected graph G. Let K be a nonempty closed subset of X and $T: K \to X$ be a G-Chatterjea contraction on K.

If $K_T := \{x \in \partial K : (x, Tx) \in E(G)\} \neq \emptyset$, T is orbitally G-continuous and T satisfies Rothe's boundary condition

$$T(\partial K) \subset K,$$

then the conclusion of Theorem 2 remains valid.

4 Conclusions and further study

The Chatterjea-type contractive condition (1.7) (or (3.5) in the non self mapping case) is independent of the Banach type contraction condition (1.3) considered in [20], and of Kannan-type contractive condition (1.6), as shown by the next examples.

Example 3. ([53], Example 1.3.1) Let X = [0, 1] with the usual norm and $T : [0, 1] \rightarrow [0, 1]$ be defined by

$$T(x) = \begin{cases} \frac{2}{5}, & x \in \left[0, \frac{2}{3}\right) \\ \\ \frac{1}{5}, & x \in \left[\frac{2}{3}, 1\right]. \end{cases}$$

Then T is a discontinuous Kannan operator with constant $a = \frac{3}{7}$, it is neither a Banach contraction nor a Chatterjea contraction.

Example 4. ([53], Example 1.3.4) Let X = [0, 1] with the usual norm and $f : [0, 1] \rightarrow [0, 1]$ be defined by

$$f(x) = \begin{cases} \frac{1}{5}, & x \in \left[0, \frac{8}{15}\right) \\ \frac{1}{3}, & x \in \left[\frac{8}{15}, 1\right]. \end{cases}$$

Then f is a Chatterjea operator with constant $a = \frac{2}{5}$ but f is neither a Banach contraction nor a Kannan contraction (see Example 1.3.7 in [53] for the proof).

This shows that Theorems 2 and 3 established in the present paper are important and very general alternative fixed point theorems for non self mappings in Banach spaces endowed with a graph. They provide effective generalisations and extensions of similar results in literature and subsume several important results in the fixed point theory of self and nonself mappings.

Both Theorem 2 and Theorem 3 were established in Banach spaces endowed with a graph for the sake of simplicity of exposition but they can be transposed in more general settings, like convex metric spaces or CAT(0)spaces without any major technical difficulty.

By working on Banach spaces endowed with a graph, our results are valid not only for mappings that satisfy the contraction condition (3.5) for all pairs (x, y) of the space $X \times X$, but only for the pairs (x, y) which are vertices of a simple directed and weakly connected graph G = (X, E(G)), with $E(G) \subset X \times X$.

Amongst the most important particular cases of Theorem 2 and Theorem 3, we mention in the following just the following ones:

1. If G is the graph G_0 in Example 1, then by Theorem 2 we obtain an extension of Chatterjea fixed point theorem [30] for non self mappings, restricted here for the reasons mentioned above to Banach spaces instead of usual complete metric spaces.

2. If K = X, and G is the graph G_0 in Example 1, then by Theorem 2 we obtain the original Chatterjea fixed point theorem [30] for self mappings, restricted here for the reasons mentioned above to Banach spaces instead of usual complete metric spaces.

For further developments, we have in view considering nonself singlevalued as well as multi-valued mappings by starting from the corresponding case of self mappings, see [1]-[4],[5], [21], [22], [25], [32], [33], [38], [39], [40], [43], [44], [50]-[59], [71]-[73], [74]-[77] etc.

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Laszlo BALOG, Department of Mathematics and Computer Science, North University Center at Baia Mare, Victoriel 76, 430122 Baia Mare Romania. Email: balog58@yahoo.com Vasile BERINDE, Department of Mathematics and Computer Science,

North University Center at Baia Mare, Victoriel 76, 430122 Baia Mare Romania. Email: vberinde@ubm.ro

Department of Mathematics and Statistics, King Fahd University of Petroleum and Minerals, Dhahran, Saudi Arabia. E-mail: vasile.berinde@gmail.com

Mădălina PĂCURAR, Department of Statistics, Analysis, Forecast and Mathematics, Faculty of Economics and Bussiness Administration, Babeş-Bolyai University of Cluj-Napoca, Cluj-Napoca Romania. Email: madalina.pacurar@econ.ubbcluj.ro